

read E&R Chapter 7
E Section 3.5

VI Bayesian Inference

① Basic Components

- we have the model for the data x

$$M = \{f_{\theta} : \theta \in \Theta\} \quad \left| \begin{array}{l} \text{one value of} \\ \theta \text{ is true.} \end{array} \right.$$

- think of f_{θ} as the conditional (prob.) dist. of x given θ

- to this we add a probab. measure for θ as given by density π called the prior

- is θ random?

- recall: probability measures beliefs concerning what is true. so

$$\pi(A) = \sum_{\theta \in A} \pi(\theta)$$

= prior probab. that true value of θ is in $A \subseteq \Theta$

- so prior and model lead to a joint probability distribution for (θ, x) given by using multiplication rule

$$\pi(\theta) f_{\theta}(x)$$

- we observe x

- principle of conditional probability

Suppose we have a prob. measure P on subsets of Ω and we make the assignment $P(A)$ to $A \subseteq \Omega$; it is our degree of belief that an outcome $\omega \in \Omega$ is in A is $P(A)$. We observe the value z_0 of a function $z: \Omega \rightarrow \mathcal{C}$ so we know that $\omega \in z^{-1}(z_0) = C$. Then we replace $P(A)$ by

$$P(A|C) = \frac{P(A \cap C)}{P(C)}$$

as our measure of belief that $\omega \in A$.

- a basic principle (axiom) of inference.

eg - rolling a symmetric die.

- $\Omega = \{1, 2, 3, 4, 5, 6\}$

- $A = \{2, 3, 6\}$, $P(A) = \frac{1}{2}$.

- told "outcome is even"

- $C = \{2, 4, 6\}$

$$P(A|C) = \frac{P(ABC)}{P(C)} = \frac{P(\{2, 6\})}{P(\{2, 4, 6\})}$$

$$= \frac{2}{3} \quad \text{betot goes up}$$

- total "outcome is divisible by 3"
 so $C = \{3, 6\}$

$$P(A|C) = \frac{P(\{3, 6\})}{P(\{3, 6\})} = 1$$

- total "outcome is odd" so $C = \{1, 3, 5\}$

$$P(A|C) = \frac{P(\{3\})}{P(\{1, 3, 5\})} = \frac{1}{3} \quad \text{betot goes down}$$

- note be careful - need to specify i (information generated)

- in the statistical problem $i(\theta, x) = x$

- principle of ambitival probability says that we replace the prior π by the posterior distribution.

$$\pi(\theta|x) = \frac{\pi(\theta) f_{\theta}(x)}{m(x)}$$

where $m(x) = \begin{cases} \sum_{\theta \in \Theta} \pi(\theta) f_{\theta}(x) & \text{discrete} \\ \int_{\Theta} \pi(\theta) f_{\theta}(x) dx & \text{cont.} \end{cases}$

is the marginal distribution of x called the prior predictive of x

- so $\pi(A)$ is replaced by

$$\pi(A|x) = \sum_{\theta \in A} \pi(\theta|x)$$

- the principle of calibrated prob says we replace the prior by the posterior for prob statements about Θ .

- what about prob. statements about $x = \overline{Y}(\theta)$

- marginal prior density $\pi_{\overline{Y}}(x) = \sum_{\theta \in \overline{Y}^{-1}(x)} \pi(\theta)$

marginal posterior density $\pi_{\overline{Y}}(x|x) = \sum_{\theta \in \overline{Y}^{-1}(x)} \pi(\theta|x)$

- predictive: suppose we have an unobserved y with conditional model $\{g_{\beta(\theta)}(y|x) : \theta \in \Theta\}$ where the same value of θ is true.

eg x = marks on assignments
 y = mark on final.

- the prior predictive for y

$$m_Y(y) = \sum_{\theta} \sum_x \pi(\theta) P_{\theta}(x) g_{\beta(\theta)}(y|x)$$

the posterior predictive for y

$$m_Y(y|x) = \frac{\text{joint for } (x,y)}{\text{marginal for } x}$$

3 variables θ, x, y

$$= \frac{\sum_{\theta} \pi(\theta) P_{\theta}(x) g_{\beta(\theta)}(y|x)}{\sum_{\theta} \sum_y \pi(\theta) P_{\theta}(x) g_{\beta(\theta)}(y|x)}$$

$$= m(x) \frac{\sum_{\theta} \pi(\theta|x) g_{\beta(\theta)}(y|x)}{\sum_{\theta} \pi(\theta|x) P_{\theta}(x)}$$

$$= m(x) \frac{\sum_{\theta} \pi(\theta|x) \sum_y g_{\beta(\theta)}(y|x)}{\sum_{\theta} \pi(\theta|x) P_{\theta}(x)}$$

$$= \sum_{\theta} \pi(\theta|x) g_{\beta(\theta)}(y|x)$$

② Prior Elicitation

- how do we choose π in a problem?
- note - fair to ask - how do we choose the model M in a problem?
 - "we choose" it - it is subjective
- we have to choose π on what we know about the measurements we are taking

eg location-scale normal

- basic measurement, $x_i \sim N(\mu, \sigma^2)$
where $\mu \in \mathbb{R}$, $\sigma^2 > 0$ are unknown.
- common choice (specify π hierarchically)

$$\mu | \sigma^2 \sim N(\mu_0, \tau_0^2 \sigma^2)$$

$$\frac{1}{\sigma^2} \sim \text{gamma}_{\text{rate}}(\alpha_0, \beta_0)$$

where $\mu_0, \tau_0^2, \alpha_0, \beta_0$ are chosen
"hyperparameters"

- joint for sample (μ, σ^2, x) where $x = (x_1, \dots, x_n)$

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$$\begin{aligned}
 & (\frac{1}{2\pi\sigma^2})^{-\frac{n}{2}} \exp\left\{-\frac{n}{2\sigma^2}(\bar{x}-\mu)^2\right\} \exp\left\{-\frac{(n+1)\sigma^2}{2\sigma^2}\right\} \times \\
 & (\frac{1}{2\pi\sigma_0^2})^{-\frac{1}{2}} \exp\left\{-\frac{1}{2\sigma_0^2}(\mu-\mu_0)^2\right\} \times \\
 & \frac{\beta_0^{\alpha_0}}{\Gamma(\alpha_0)} \left(\frac{1}{\sigma^2}\right)^{\alpha_0-1} \exp\left\{-\beta_0/\sigma^2\right\}
 \end{aligned}$$

posterior

$$\begin{aligned}
 \propto & \exp\left\{-\frac{1}{2\sigma^2} \left[n(\bar{x}-\mu)^2 + \frac{1}{\sigma_0^2} (\mu-\mu_0)^2 \right]\right\} \times \\
 & \left(\frac{1}{\sigma^2}\right)^{\frac{n+1+\alpha_0}{2}-1} \exp\left\{-\frac{[n+1]\bar{x}^2 + \beta_0}{\sigma^2}\right\}
 \end{aligned}$$

$$\begin{aligned}
 & n(\bar{x}-\mu)^2 + \frac{1}{\sigma_0^2} (\mu-\mu_0)^2 \\
 = & n\bar{x}^2 - 2n\bar{x}\mu + n\mu^2 + \frac{1}{\sigma_0^2} \mu^2 - 2\frac{\mu_0}{\sigma_0^2} \mu + \frac{\mu_0^2}{\sigma_0^2} \\
 = & \left(n + \frac{1}{\sigma_0^2}\right) \mu^2 - 2\left(n\bar{x} + \frac{\mu_0}{\sigma_0^2}\right) \mu + n\bar{x}^2 + \frac{\mu_0^2}{\sigma_0^2} \\
 = & \left(n + \frac{1}{\sigma_0^2}\right) \left(\mu - \frac{\left(n\bar{x} + \frac{\mu_0}{\sigma_0^2}\right)}{\left(n + \frac{1}{\sigma_0^2}\right)}\right)^2 \\
 & - \frac{\left(n + \frac{1}{\sigma_0^2}\right)^{-1} \left(n\bar{x} + \frac{\mu_0}{\sigma_0^2}\right)^2}{\left(n + \frac{1}{\sigma_0^2}\right)} + n\bar{x}^2 + \frac{\mu_0^2}{\sigma_0^2} \\
 = & \left(\dots\right) - \frac{\left(n + \frac{1}{\sigma_0^2}\right)^{-1} \left(n^2\bar{x}^2 + 2n\bar{x}\frac{\mu_0}{\sigma_0^2} + \frac{\mu_0^2}{\sigma_0^2}\right)}{\left(n + \frac{1}{\sigma_0^2}\right)} \\
 & + n\bar{x}^2 + \frac{\mu_0^2}{\sigma_0^2} \\
 = & \left(\dots\right) + \left(\frac{n + \frac{1}{\sigma_0^2}}{n + \frac{1}{\sigma_0^2} + 1}\right) \bar{x}^2 - \frac{2n\bar{x}\mu_0}{n + \frac{1}{\sigma_0^2} + 1} + \frac{\mu_0^2}{n + \frac{1}{\sigma_0^2} + 1}
 \end{aligned}$$

$$= () + \frac{n}{n\tau_0^2 + 1} x^2 - \frac{2n}{n\tau_0^2 + 1} \bar{x} \mu_0 + \frac{n\tau_0^2}{n\tau_0^2 + 1} \frac{1}{\tau_0^2} \mu_0^2$$

$$= () + \frac{n}{n\tau_0^2 + 1} (\bar{x} - \mu_0)^2$$

$$\propto \left(\frac{1}{\sigma^2}\right)^{\frac{1}{2}} \exp\left\{-\frac{1}{2\sigma^2} \left(n + \frac{1}{\tau_0^2}\right) \left(\mu - \left(n + \frac{1}{\tau_0^2}\right)^{-1} \left(n\bar{x} + \frac{\mu_0}{\tau_0^2}\right)\right)^2\right\}$$

$$\times \left(\frac{1}{\sigma^2}\right)^{\frac{n+\tau_0^2}{2}} \exp\left\{-\left[\frac{(n-1)s^2}{2} + \beta_0 + \frac{1}{2} \frac{n}{n\tau_0^2 + 1} (n\bar{x} + \frac{\mu_0}{\tau_0^2})^2\right] / \frac{1}{\sigma^2}\right\}$$

$$\therefore \mu | x, \sigma^2 \sim N\left(\left(n + \frac{1}{\tau_0^2}\right)^{-1} \left(n\bar{x} + \frac{\mu_0}{\tau_0^2}\right), \left(n + \frac{1}{\tau_0^2}\right)^{-1} \sigma^2\right)$$

$$\frac{1}{\sigma^2} | x \sim \text{gamma rate} \left(\frac{n+\tau_0^2}{2}, \underbrace{\beta_0 + \frac{(n-1)s^2}{2} + \frac{1}{2} \frac{n}{n\tau_0^2 + 1} \left(n\bar{x} + \frac{\mu_0}{\tau_0^2}\right)^2}_{\beta_x}\right)$$

note - the posterior is of the same form as the prior

- the prior is said to be conjugate.

note can generate from the prior and posterior by first generating $\mu | \sigma^2$ and then generating μ, σ^2

- still how do we select $\mu_0, \tau_0^2, \alpha_0, \beta_0$?

elicitation

- suppose we are measuring heights of students at U of T (in same units) \approx
 μ = mean height, σ^2 = variance of hts

- specify (m_1, m_2) so that you believe that $\mu \in (m_1, m_2)$ with virtual certainty (say prob $\geq .99$) and put $\mu_0 = (m_1 + m_2) / 2$

$$\begin{aligned}
 - \text{so } 0.99 &\leq \Phi\left(\frac{m_2 - \mu_0}{\tau_0 \sigma}\right) - \Phi\left(\frac{m_1 - \mu_0}{\tau_0 \sigma}\right) \\
 &= \Phi\left(\frac{(m_2 - m_1) / 2}{\tau_0 \sigma}\right) - \Phi\left(-\frac{(m_2 - m_1) / 2}{\tau_0 \sigma}\right) \\
 &= 2 \Phi\left(\frac{m_2 - m_1}{2 \tau_0 \sigma}\right) - 1
 \end{aligned}$$

iff $\frac{1 + 0.99}{2} = 0.995 \leq \Phi\left(\frac{m_2 - m_1}{2 \tau_0 \sigma}\right)$

iff $z_{0.995} = \Phi^{-1}(0.995) \leq \frac{m_2 - m_1}{2 \tau_0 \sigma}$

$z_{0.995} = 2.576$

iff $\sigma \leq \frac{m_2 - m_1}{2 \tau_0 z_{0.995}}$ (*) | haven't prescribed τ_0 yet

- we know a measurement lies in $(\mu - \sigma z_{0.995}, \mu + \sigma z_{0.995})$ with virtual certainty

- let s_1, s_2 be lower and upper bounds on the half-length of this interval

$$s_1 \leq \sigma z_{0.995} \leq s_2 \quad \text{or} \quad z_{0.995}^2 \leq \frac{1}{\tau^2} \leq z_{0.995}^2$$

- combining this with $\textcircled{4}$ gives.

$$\frac{m_2 - m_1}{z_{0.995} \sqrt{s_2}} = \frac{s_2}{z_{0.995}}$$

or $\sigma_0 = \frac{m_2 - m_1}{z_{0.995}}$ so (μ_0, σ_0) is determined

- need to determine (α_0, β_0)

- let $G(\alpha, \beta, \cdot)$ denote the gamma (α, β) cdf with quantiles fn $G^{-1}(\alpha, \beta, \cdot)$, note $G(\alpha, \beta, x) = G(\alpha, 1, \beta x)$

- so we want α, β st

$$G(\alpha, \beta, \frac{z_{0.995}^2}{s_1}) = 0.995$$

$$G(\alpha, \beta, \frac{z_{0.005}^2}{s_2}) = 0.005$$

- do this iteratively pick α_0 and find w_0 st. $G^{-1}(\alpha_0, 1, 0.995) = w_0$ so $\beta_0 = w_0^2 / z_{0.995}^2$

- if $G(\alpha_0, 1, \beta_0 \frac{z_{0.995}^2}{s_1}) < 0.995$ then decrease α_0 and repeat

- in general: statistical analyses requires an elicitation procedure like this
- note - if $\pi(\theta) = 0$ then $\pi(\theta|x) = \frac{\pi(\theta) f_{\theta}(x)}{\text{total}} = 0$
 so never put 0 mass at θ unless you categorically know that θ is false.

③ Checking the Ingredients

- we have chosen a model $\{P_\theta : \theta \in \Theta\}$ and a prior π
- do these choices make sense?
- how do we assess this?
- principle of empirical criticism

Any ingredient chosen to be part of a statistical analysis must be checked against the objective data to see if there is any indication it is a bad choice.

- note - we can never say a choice is correct only that it is not clearly wrong and so potentially misleading

- note - an important corollary of the principle: if inferences depend on ingredients that cannot be checked against the data, then the analysis must be so qualified

- note - we want to check the model first and then the prior

- how?
- let T be a MSS for the model
- we have the joint dist of (θ, x)

$$\begin{aligned} \pi(\theta) f_{\theta}(x) &= \pi(\theta) f_{\theta, T}(T(x)) f(x|T(x)) \\ &= \pi(\theta|T(x)) m_T(T(x)) f(x|T(x)) \end{aligned}$$

- note

$$\begin{aligned} \pi(\theta|x) &= \frac{\pi(\theta) f_{\theta}(x)}{m(x)} = \frac{\pi(\theta) f_{\theta, T}(T(x)) f(x|T(x))}{\sum_{\theta} f_{\theta, T}(T(x)) f(x|T(x))} \\ &= \frac{\pi(\theta) f_{\theta, T}(T(x))}{m_T(T(x))} \end{aligned}$$

$$\begin{aligned} m(x) &= m_T(T(x)) \\ & f(x|T(x)) \end{aligned}$$

so posterior only depends on data through T .

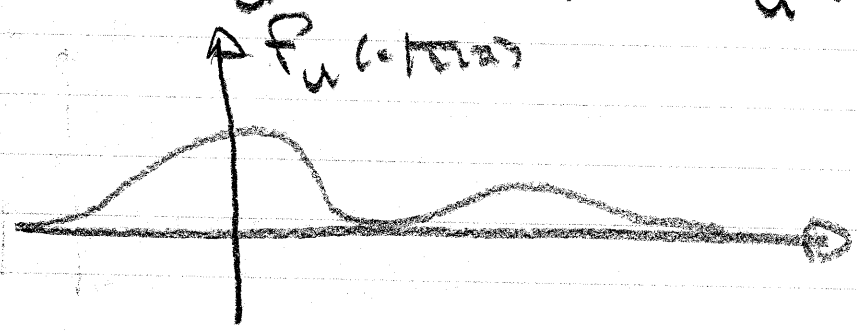
- joint posterior into $\pi(\theta|T(x))$ probs for θ
 $m_T(T(x))$ checking the prior
 $f(x|T(x))$ checking the model

- checking the model

- let $U(x)$ be a discrepancy statistic in the sense that "large" values of $U(x)$ indicate model failure.

- the compute:

$$P(F_U(u|\tau(x)) \leq F_U(U(x)|\tau(x)))$$



- a small tail prob indicates problems with the model.

~~Q~~ $x = (x_1, \dots, x_n) \stackrel{iid}{\sim} \mathcal{N}(\mu, \sigma^2), z \sim \mathcal{N}_n(\mu, \sigma^2 I)$

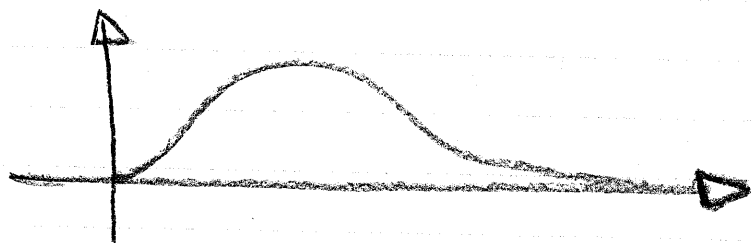
- $T(x) = \bar{x}$

- $\underline{x} = \bar{x}_1 + (\underline{x} - \bar{x}_1)$

- $\underline{x} - \bar{x}_1 = \left(I - \frac{1}{n} \begin{pmatrix} 1 & 1 & \dots & 1 \\ 1 & 1 & \dots & 1 \\ \vdots & \vdots & \ddots & \vdots \\ 1 & 1 & \dots & 1 \end{pmatrix} \right) \underline{x}$
 $\sim \mathcal{N}\left(\underline{0}, \sigma^2 \left(I - \frac{1}{n} \begin{pmatrix} 1 & 1 & \dots & 1 \\ 1 & 1 & \dots & 1 \\ \vdots & \vdots & \ddots & \vdots \\ 1 & 1 & \dots & 1 \end{pmatrix} \right) \right)$ ind of \bar{x}

- $U(x) = \|\underline{x} - \bar{x}_1\|^2 \sim \sigma^2 \text{chi-squared}(n-1)$

$$\therefore P(f_u(u|T(x)) \leq f_u(u(x)|T(x)))$$



$$= P\left(x^{\frac{n-1}{2}} e^{-\frac{x^2}{2}} \leq (n\bar{x} - \bar{x}_1)^2 e^{-\frac{n\bar{x} - \bar{x}_1}{2}}\right)$$

and compute using simulation.

$\vec{x} = (x_1, \dots, x_n)' \sim N(\mu, \sigma^2)$ $\mu \in \mathbb{R}^1, \sigma^2 > 0$

$\vec{x} \sim N_n(\mu_n, \sigma^2 I)$

$\vec{x} = \bar{x}_1 + \frac{\|\vec{x} - \bar{x}_1\|}{\|\vec{x} - \bar{x}_1\|} \left(\frac{\vec{x} - \bar{x}_1}{\|\vec{x} - \bar{x}_1\|} \right)$

$\vec{x} \sim N(\mu, \sigma^2/n)$

$\|\vec{x} - \bar{x}_1\|^2 \sim \sigma^2 \text{ChiSq}(n-1)$

$\frac{\vec{x} - \bar{x}_1}{\|\vec{x} - \bar{x}_1\|} \sim U(S^{n-1} \cap \mathbb{R}^n)$

independent

$$U(\vec{x}) = \frac{1}{n} \prod_{i=1}^n \frac{(x_i - \bar{x}_1)^3}{\|\vec{x} - \bar{x}_1\|^3}$$

stance.

$$= U\left(\frac{\vec{x} - \bar{x}_1}{\|\vec{x} - \bar{x}_1\|}\right)$$

- need to compute

$$P \left(\hat{f}_u(u | T(x)) \leq f_u(u(x) | T(x)) \mid T(x) \right)$$

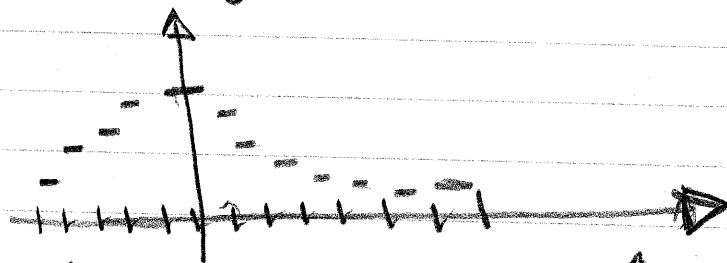
(recall u is i.i.d of \mathcal{U})

$$= P \left(\hat{f}_u(u) \leq f_u(u(x)) \right)$$

algorithm: - generate $z_1, \dots, z_N \stackrel{i.i.d.}{\sim} N_n(\mathbf{0}, \mathbf{I})$

- compute $u_i = u(z_i)$ $i=1, \dots, n$
which gives a sample of n from f_u

- compute estimate \hat{f}_u via a density estimation algorithm, e.g. density histograms



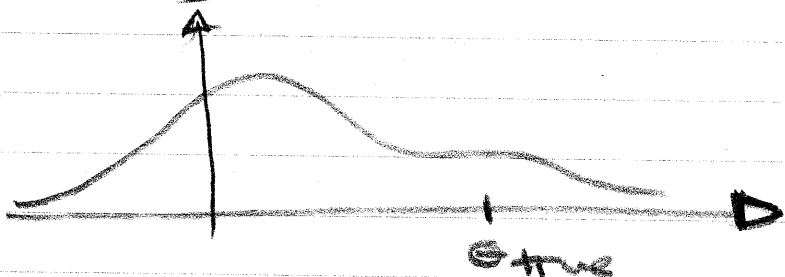
and record proportion $\hat{F}_u(u_i) \leq \hat{f}_u(u(x))$

- what to do if the model fails?

checking the prior

- is θ_{true} a plausible value for π ?

- measure by $\pi (\pi(\theta) \leq \pi(\theta_{true}))$



- but we don't know θ_{true}

- Fact - under conditions (TMS)

$$M_T (m_T(\theta) \leq m_T(\tau(\alpha)))$$

$$\rightarrow \pi (\pi(\theta) \leq \pi(\theta_{true}))$$

- \therefore check the prior by computing θ

- actually you can check individual components of a prior

Examples

① - $x = (x_1, \dots, x_n)' \sim N(\mu, 1)$

- $\mu \sim N(\mu_0, \tau_0^2)$

- $T(x) = \bar{x} = \mu + z/\tau_n$ ^{Prior} $\sim N(\mu_0, \tau_0^2 + 1/n)$

- so $m_T(x) = (2\pi)^{-1/2} (\tau_0^2 + 1/n)^{-1/2} \exp\left\{-\frac{(\tau_0^2 + 1/n)^{-1}}{2} (x - \mu_0)^2\right\}$

- $m_T(m_T(x) \leq m_T(\bar{x}))$

$= m_T\left((\tau_0^2 + 1/n)^{-1} (x - \mu_0)^2 \geq (\tau_0^2 + 1/n)^{-1} (\bar{x} - \mu_0)^2\right)$

$= z(1 - \Phi((\tau_0^2 + 1/n)^{-1/2} |\bar{x} - \mu_0|))$

$\rightarrow z(1 - \Phi\left(\left|\frac{\mu_{true} - \mu_0}{\tau_0}\right|\right)) = \pi(\mu) \leq \pi(\mu_{true})$
as $n \rightarrow \infty$

$\rightarrow (1 - \Phi(z)) = 1$ as $\tau_0^2 \rightarrow \infty$

- so large τ_0^2 avoids prior-data conflict

eg 2 $x = (x_1, \dots, x_n) \sim \text{Bernoulli}(\theta)$

- $\theta \sim U(0,1)$ (non-informative?)

- $T(x) = n\bar{x}$ is MSS

$\sim \text{Binomial}(n, \theta)$

- $m_T(t) = \int_0^1 \binom{n}{t} \theta^t (1-\theta)^{n-t} d\theta$

$= \binom{n}{t} \frac{\Gamma(t+1)\Gamma(n-t+1)}{\Gamma(n+2)} = n! \frac{t!(n-t)!}{t!(n-t)!(n+1)!} = \frac{1}{n+1}$

- $m_T(m_T(t) \leq m_T(\bar{x})) = 1 = \mathbb{P}(\pi(\theta) \leq \pi(\bar{x}))$
and never my indicator of prior data cut off

- $\theta \sim \text{beta}(\alpha, \beta)$ $\theta | x \sim \text{beta}(n\bar{x} + \alpha, n(1-\bar{x}) + \beta)$ so conjugate

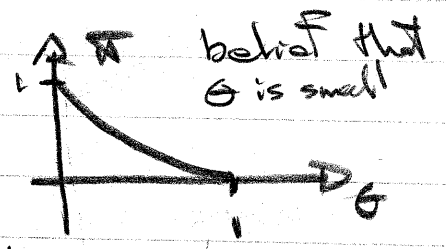
$m_T(t) = \frac{\Gamma(n+1)}{\Gamma(t+1)\Gamma(n-t+1)} \frac{\Gamma(\alpha)\Gamma(\beta)}{\Gamma(\alpha+\beta)} \frac{\Gamma(n\bar{x} + \alpha)\Gamma(n(1-\bar{x}) + \beta)}{\Gamma(n+1 + \alpha + \beta)}$

eg 3 $y \sim \text{Geometric}(\theta)$ $\theta \in (0,1]$

- $f_\theta(y) = \theta(1-\theta)^{y-1}$ $y \in \{1,2,\dots\}$ note.

- $T(y) = y$ is a MSS (E_x)

- $\theta \sim \text{Beta}(1, c)$ with $c > 1$
so $\pi(\theta) = \frac{\Gamma(1+c)}{\Gamma(1)\Gamma(c)} (1-\theta)^{c-1}$



- $m_T(t) = \int_0^1 \theta(1-\theta)^{c+t-2} d\theta$

\int_{c-1}^1

$$\Gamma(c_{t+1}) = a \Gamma(c_t)$$

(20)

$$= c \frac{\Gamma(z) \Gamma(c_{t+1} - 1)}{\Gamma(c_{t+1})} = c \frac{(c_{t+1} - 2) \Gamma(c_{t+1} - 1)}{(c_{t+1})(c_{t+1} - 1) \Gamma(c_{t+1} - 2)}$$

$$- M_T (m_T(t) \leq m_T(y))$$

$$\ln |m_T(t)| = \ln c - \ln(c_{t+1}) - \ln(c_{t+1} - 1)$$

$$\frac{\partial}{\partial t} = -\frac{1}{c_{t+1}} - \frac{1}{c_{t+1} - 1} < 0 \text{ all}$$

so strictly decreasing in t

$$= \sum_{t=y}^{\infty} \frac{c}{(c_{t+1})(c_{t+1} - 1)} = -c \sum_{t=y}^{\infty} \left(\frac{1}{c_{t+1}} - \frac{1}{c_{t+1} - 1} \right)$$

$$= -c \left(-\frac{1}{c+y-1} \right) = \frac{c}{c+y-1} = \frac{1}{1 + \frac{y-1}{c}}$$

all so we get prior-data conflict when $\left(\frac{y}{c}\right)$ is big as we need lots of tosses to get a $\#$

- note - when $c=1$ then $\theta \sim U(0,1]$, Probab is $1/4$

- why not 1 as with Binomial?

- the bigger c is the more mass we have around 0 but recall $\theta \neq 0$

- in terms of the cut approx this means θ cannot be very small
- a large value of y indicates θ is small and so indicates prior-data conflict

- note - suppose $\theta \in \{ \frac{1}{2}, \frac{2}{3}, \dots, 1 \}$ equiprobable

$$m_T(\theta) = \frac{1}{2} \prod_{i=1}^T \frac{1}{2} (1 - \frac{i}{2})^{\theta-1}$$

$$\frac{\partial m_T(\theta)}{\partial \theta} = \frac{1}{2} \prod_{i=1}^T \left[\ln(1 - \frac{i}{2}) \right] \frac{1}{2} (1 - \frac{i}{2})^{\theta-1} < 0$$

so decreasing in θ

$$M_T(m_T(\theta) \leq m_T(y))$$

$$\begin{aligned} &= \sum_{\theta=1}^N \frac{1}{2} \prod_{i=1}^T \frac{1}{2} (1 - \frac{i}{2})^{\theta-1} \\ &= \frac{1}{2} \prod_{i=1}^T \frac{1}{2} (1 - \frac{i}{2})^{y-1} \sum_{\theta=0}^N (1 - \frac{i}{2})^{\theta} \\ &= \frac{1}{2} \prod_{i=1}^T \frac{1}{2} (1 - \frac{i}{2})^{y-1} \frac{1 - (1 - \frac{i}{2})^{N+1}}{1 - (1 - \frac{i}{2})} \\ &= \frac{1}{2} \prod_{i=1}^T \frac{1}{2} (1 - \frac{i}{2})^{y-1} \sum_{x=0}^N (1 - \frac{i}{2})^x \end{aligned}$$

location-scale normal

- $x = (x_1, \dots, x_n) \stackrel{iid}{\sim} N(\mu, \sigma^2)$

$\mu | \sigma^2 \sim N(\mu_0, \tau_0^2 \sigma^2)$

$\frac{1}{\sigma^2} \sim \text{gamma rate}(\alpha_0, \beta_0) = \frac{1}{2\beta_0} \text{chi-squared}(2\alpha_0)$

- MSS $T(x) = (T_1(x), T_2(x)) = (\bar{x}, \frac{1}{n} \|x - \bar{x}\|^2)$

$\bar{x} | \mu, \sigma^2 \sim N(\mu, \frac{\sigma^2}{n})$ ind of $\frac{1}{n} \|x - \bar{x}\|^2 \sim \sigma^2 \text{chi-squared}(n-1)$
 $= \text{gamma}(\frac{n-1}{2}, \frac{1}{2\sigma^2})$

- we check the prior on σ^2 first via

$M_{T_2} (m_{T_2}(x_2) \leq m_{T_2}(T_2(x)))$

- so we need m_{T_2}

$x_2 = \mu_0 + \sigma^2 \frac{1}{n} \|x - \bar{x}\|^2$
 $= \sigma^2 \frac{1}{n} \|x - \bar{x}\|^2$

- $\frac{1}{n} \|x - \bar{x}\|^2 \sim X_1 / X_2$ where X_1, X_2 ind

$\sim \frac{\text{chi-squared}(n-1)}{\text{gamma rate}(\alpha_0, \beta_0)}$

$\frac{\beta_0^{\alpha_0}}{\Gamma(\alpha_0)} x_2^{\alpha_0-1} e^{-\beta_0 x_2} = \frac{1}{\Gamma(\frac{2\alpha_0}{2})} \left(\frac{2\beta_0 x_2}{2}\right)^{\frac{2\alpha_0}{2}-1} e^{-2\beta_0 x_2 / 2}$

$= \frac{1}{2\beta_0} \text{chi-squared}(2\alpha_0) \text{ density}$

$$\begin{aligned} \therefore \| \hat{\alpha}_0 - \alpha_0 \|^2 &\sim (n-1) \frac{2\beta_0}{2\alpha_0} \frac{\chi^2_{n-1}}{n-1} / \frac{2\beta_0 \chi^2_2}{2\alpha_0} \\ &\sim (n-1) \frac{\beta_0}{\alpha_0} \Gamma(n-1, 2\alpha_0) \end{aligned}$$

$$\therefore m_{T_2}(t_2) = \frac{\Gamma\left(\frac{n-1+2\alpha_0}{2}\right) \left(\frac{\alpha_0}{n-1\beta_0} \frac{\alpha-1}{2\alpha_0} t_2\right)^{\frac{n-1}{2}-1}}{\Gamma\left(\frac{n-1}{2}\right) \Gamma\left(\frac{2\alpha_0}{2}\right) \left(1 + \frac{\alpha_0}{\beta_0} \frac{\alpha-1}{2\alpha_0} t_2\right)^{\frac{n-1+2\alpha_0}{2}}} \frac{1}{2\beta_0}$$

and then $M_{T_2}(m_{T_2}(t_2) \leq m_{T_2}(T_2(x)))$

can be computed via simulation on T_2

- if the prior on σ^2 passes then check the prior on μ via

$$M_{T_1}(m_{T_1}(t_1) \leq m_{T_1}(T_1(x)))$$

- so we need m_{T_1}

$$\begin{aligned} T_1(x) = \bar{x} &= \mu + \sigma \frac{Z}{\sqrt{n}} \stackrel{N(0,1)}{=} \mu_0 + \tau_0 \sigma u + \sigma \frac{1}{\sqrt{n}} Z \\ &= \mu_0 + \sigma \left(\tau_0 u + \frac{1}{\sqrt{n}} Z \right) \end{aligned}$$

$$\therefore \bar{x} | \sigma^2 \sim N\left(\mu_0, \sigma^2 \left(\tau_0^2 + \frac{1}{n}\right)\right)$$

$$\therefore \frac{\bar{x} - \mu_0}{\sqrt{\tau_0^2 + \frac{1}{n}} \sigma} = \frac{\bar{x} - \mu_0}{\sqrt{\chi^2_2}}$$

$$= \frac{N(0,1)}{\sqrt{\frac{2x_0}{2\beta_0} \text{chi-squared}(2x_0)}} = \sqrt{\frac{\beta_0}{\alpha_0}} \tau_{2x_0}$$

$$\therefore m_{T_2}(t_2) = \frac{\Gamma(\frac{2x_0+1}{2})}{\Gamma(\frac{1}{2})\Gamma(\frac{2x_0}{2})} \left(1 + \frac{\alpha_0}{\beta_0 2x_0} \left(\frac{2x_0 - M_2}{\sqrt{2x_0+1}}\right)^2\right)^{-\frac{2x_0+1}{2}} \frac{1}{\sqrt{2\beta_0} \sqrt{2x_0+1}}$$

then compute $m_{T_1}(m_{T_2}(t_2)) \approx m_{T_1}(T_1(x_2))$
 via simulation from t_1

4. Inference

- different approaches to inference about $\theta = \mathbb{R}(\theta)$

(a) Bayesian Decision Theory

- we add another ingredient, namely a loss function $L: \mathbb{R} \times \mathbb{R} \rightarrow [0, \infty)$ where $L(\theta, a) = 0$ iff $a = \mathbb{R}(\theta)$

- but - this viciates the principle of empirical criticism as there is no way to falsify the choice of L

- we prefer theories of inference that don't contain unfalsifiable elements.

- in any case.

- the theory adds a principle

Principle of Minimal ^{Expected} Loss (or Maximal ^{Expected} Utility where utility fn is $U(\theta, a) = -L(\theta, a)$)

Choose decision fn $\delta: \mathcal{X} \rightarrow \mathbb{I}$ that minimizes

$$r(\delta) = \mathbb{E}(L(\theta, \delta(\theta)))$$

$$\begin{aligned} r(s) &= \int_{\Theta} \int_{\mathcal{X}} L(\theta, s(x)) \pi(\theta) f_{\theta}(x) dx d\theta \\ &= \int_{\Theta} R_{\theta}(s) \pi(\theta) d\theta. \end{aligned} \quad (26)$$

where \mathbb{E} is taken with respect to the joint distribution of (θ, x)

- $r(s)$ is called the prior risk

- s_0 satisfying $r(s_0) \leq r(s)$ for all s is called a Bayes rule and $r(s_0)$ is called the Bayes risk

note
Lemma A Bayes rule is obtained by minimizing the posterior risk for each $x \in \mathcal{X}$.

Proof: We have that

$$\begin{aligned} r(s) &= \int_{\Theta} \int_{\mathcal{X}} L(\theta, s(x)) \pi(\theta) f_{\theta}(x) dx d\theta \\ &= \int_{\mathcal{X}} \int_{\Theta} L(\theta, s(x)) \pi(\theta) f_{\theta}(x) \underbrace{m(x)}_{\text{marginal}} dx d\theta \\ &= \int_{\mathcal{X}} \left(\int_{\Theta} L(\theta, s(x)) \pi(\theta) dx \right) m(x) dx \\ &= \int_{\mathcal{X}} r(s(x)) m(x) dx \end{aligned}$$

and the result follows.

the posterior risk at s .

Quadratic loss

- suppose $\mathcal{F} \subseteq \mathbb{R}^k$ is convex and
 $L(\theta, a) = \|\mathcal{F}(\theta) - a\|^2$
- so we want $s(x) \in \mathcal{F}$ that minimizes

$$\begin{aligned}
 T(s|x) &= \mathbb{E}_{\pi(x)} (\|\mathcal{F}(\theta) - s(x)\|^2) \\
 &= \mathbb{E}_{\pi_{\mathcal{F}}(x)} (\|\pi - s(x)\|^2) \\
 &= \mathbb{E}_{\pi_{\mathcal{F}}(x)} (\|\pi - \mathbb{E}_{\pi_{\mathcal{F}}(x)}(\pi) + \mathbb{E}_{\pi_{\mathcal{F}}(x)}(\pi) - s(x)\|^2) \\
 &= \mathbb{E}_{\pi_{\mathcal{F}}(x)} (\|\pi - \mathbb{E}_{\pi_{\mathcal{F}}(x)}(\pi)\|^2) \\
 &\quad + 2 \mathbb{E}_{\pi_{\mathcal{F}}(x)} ((\pi - \mathbb{E}_{\pi_{\mathcal{F}}(x)}(\pi))' (\mathbb{E}_{\pi_{\mathcal{F}}(x)}(\pi) - s(x))) \\
 &\quad + \mathbb{E}_{\pi_{\mathcal{F}}(x)} (\|\mathbb{E}_{\pi_{\mathcal{F}}(x)}(\pi) - s(x)\|^2) \quad = 0 \\
 &= \mathbb{E}_{\pi_{\mathcal{F}}(x)} (\|\pi\|^2) + 2(\mathbb{E}_{\pi_{\mathcal{F}}(x)}(\pi) - \mathbb{E}_{\pi_{\mathcal{F}}(x)}(\pi))' (\mathbb{E}_{\pi_{\mathcal{F}}(x)}(\pi) - s(x)) \\
 &\quad + \|\mathbb{E}_{\pi_{\mathcal{F}}(x)}(\pi) - s(x)\|^2 \\
 &\geq \mathbb{E}_{\pi_{\mathcal{F}}(x)} (\|\pi - \mathbb{E}_{\pi_{\mathcal{F}}(x)}(\pi)\|^2) \quad \text{with equality} \\
 \therefore \text{PF } s(x) &= \mathbb{E}_{\pi_{\mathcal{F}}(x)}(\pi)
 \end{aligned}$$

∴ provided the posterior expectation exists the Bayes rule is given by the posterior mean of τ .

- but dependent on loss

eg hypothesis testing

- $\Theta = H_0 \cup H_a, H_0 \cap H_a = \emptyset$

- $L: \Theta \times \{0,1\} \rightarrow \mathbb{R}$
 where $L(\theta, \tau) = \begin{cases} 1 & \theta \in H_0, \tau = 1 \\ 0 & \text{otherwise} \end{cases}$
 where $S(x) = \begin{cases} 1 & \theta \in H_0, \tau = 1 \text{ or } \theta \in H_a, \tau = 0 \\ 0 & \text{otherwise} \end{cases}$
 and $S(x) = 0$
 means reject H_0
 means accept H_0

$\int_{H_0} \pi(\theta) = \int_{H_0} I(\theta)$

- $r(S|x) = \int_{\Theta} \pi(\theta|x) L(\theta, S(x))$

$= \begin{cases} \pi(H_0|x) & \text{if } S(x) = 1 \\ \pi(H_a|x) & \text{if } S(x) = 0 \end{cases}$

∴ put $S(x) = 1$ if $\pi(H_0|x) \leq \pi(H_a|x)$
 and 0 otherwise.

- so reject H_0 whenever posterior prob. of H_0 is \leq posterior prob of H_a

- but - suppose $\pi(H_0) = 0$ say $H_0 = \overline{\pi^{-1}(\epsilon_{H_0})}$
 and π_{H_a} is continuous then
 $\pi(H_0) = \int_{\pi^{-1}(0)} \pi_{H_a}(\theta) d\theta = 0$

- then $\pi(H_0|x) = 0$ and we always reject H_0 which is ridiculous

- various fixes (later)

- note - no assessment of accuracy of estimate or strength of evidence

(b) MAP (maximum a posteriori) inference

- inference about $\theta = \underline{\theta}(\omega)$

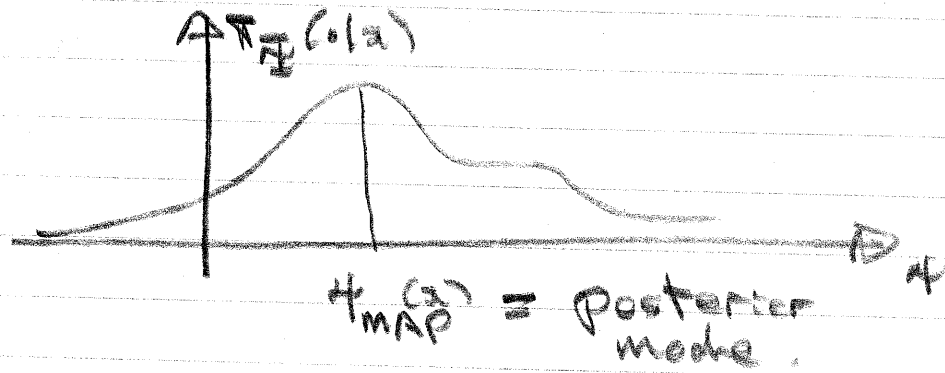
- MAP preference ordering:

we prefer θ_1 to θ_2 whenever $\pi_{\underline{\theta}}(\theta_1 | x) \geq \pi_{\underline{\theta}}(\theta_2 | x)$

- so we prefer θ_1 to θ_2 whenever we are more confident that θ_1 is the true value is, than our belief that θ_2 is the true value.

- estimation: $\theta_{MAP}(x)$ satisfies

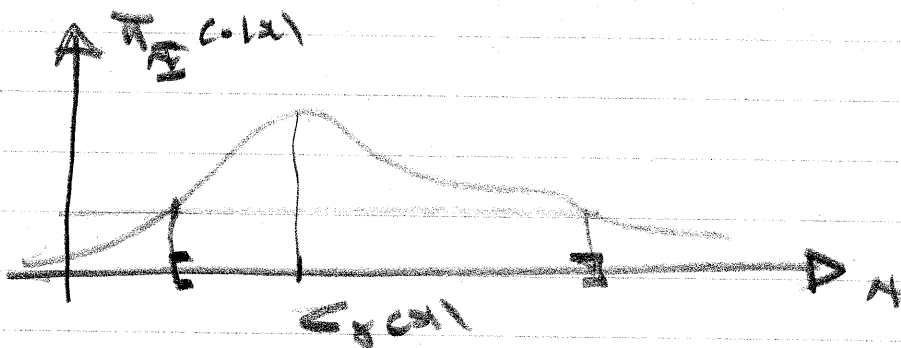
$$\pi_{\underline{\theta}}(\theta | x) \leq \pi_{\underline{\theta}}(\theta_{MAP}(x) | x), \quad \forall \theta \in \underline{\Theta}$$



- to assess accuracy $\theta_{MAP}(x)$ compute the following δ -credible region where we choose $\delta \in [0, 1]$ (say $\delta = 0.95$)

$$C_{\delta}(x) = \{ \theta \mid \pi_{\underline{\theta}}(\theta | x) \geq c_{\delta}(x) \}$$

- to see what $C_{\delta}(x)$ is, let $G_{\mathbb{H}}(\cdot | x)$ be the cdf of $\pi_{\mathbb{H}}(\cdot | x)$ when $\pi \sim \mathbb{H}(\cdot | x)$
- so $C_{\delta}(x) = G_{\mathbb{H}}^{-1}(1 - \delta | x)$



- note $\pi_{\text{MAP}}(x) \in C_{\delta_1}(x) \subseteq C_{\delta_2}(x)$ whenever $\delta_1 \leq \delta_2$

- so look at "size" of $C_{\delta}(x)$ to assess the accuracy of $\pi_{\text{MAP}}(x)$

eg location-scale normal

- $x = (x_1, \dots, x_n) \stackrel{\text{iid}}{\sim} N(\mu, \sigma^2)$
 $\mu | \sigma^2 \sim N(\mu_0, \tau_0^2 \sigma^2)$, $1/\sigma^2 \sim \text{gamma rate}(\alpha_0, \beta_0)$

- we should $\mu | x, \sigma^2 \sim N\left((n + \frac{1}{\tau_0^2})^{-1} (n\bar{x} + \frac{\mu_0}{\tau_0^2}), (n + \frac{1}{\tau_0^2}) \sigma^2\right)$

$$\frac{1}{\sigma^2} | x \sim \text{gamma rate} \left(\frac{n + 2\alpha_0}{2}, \frac{(n-1)s_x^2}{2} + \frac{1}{2} \frac{n}{2\tau_0^2} (\bar{x} - \mu_0)^2 \right)$$

$$\sigma^2 \sim \text{gamma} \left(\frac{n + 2\alpha_0}{2}, \frac{1}{2\beta_0} \right) \text{ density}$$

$$\mu = \frac{(n + \frac{1}{\tau_0^2})^{-1} (n\bar{x} + \frac{M_0}{\tau_0^2})}{n + \frac{1}{\tau_0^2}} \sim Z / \sqrt{\frac{1}{\tau_0^2}}$$

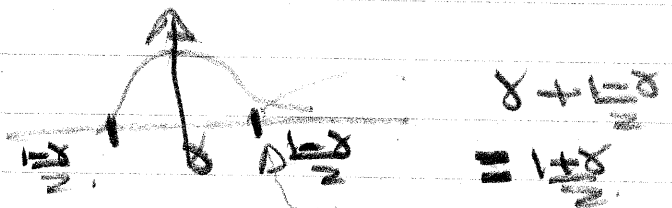
$$Z / \sqrt{(n + \frac{1}{\tau_0^2}) \frac{\sigma^2}{2\beta_2(n + \frac{1}{\tau_0^2})}}$$

$$= \sqrt{\frac{2\beta_2}{n + \frac{1}{\tau_0^2}}} \tau_{n + \frac{1}{\tau_0^2}}$$

- MAP estimator of μ is

$$\mu_{MAP}(x) = (n + \frac{1}{\tau_0^2})^{-1} (n\bar{x} + \frac{M_0}{\tau_0^2})$$

- δ -credible region is



$$(n + \frac{1}{\tau_0^2})^{-1} (n\bar{x} + \frac{M_0}{\tau_0^2}) \pm \sqrt{n + \frac{1}{\tau_0^2}} \sqrt{\frac{2\beta_2}{n + \frac{1}{\tau_0^2}}} \tau_{n + \frac{1}{\tau_0^2}}$$

- hypothesis assessment $H_0 = \mathbb{I}^{-1}(\epsilon | t_0)$

- compute the Bayesian p-value.

$$\mathbb{I}_{\mathbb{I}} \left(\pi_{\mathbb{I}}(H | x) \leq \pi_{\mathbb{I}}(t_0 | x) \mid x \right)$$

all say evidence against H_0 when small

- note Bayesian p-value $< 1 - \delta$ iff $t_0 \notin C_{\delta(x)}$

by location-scale normal (cont'd)

- consider $\mathbb{I}(\mu, \sigma^2) = \mu$, $H_0: \mu = \mu_0$

$$\mathbb{I}_{\mathbb{I}} \left(\pi_{\mathbb{I}}(\mu | x) \leq \pi_{\mathbb{I}}(\mu_0 | x) \mid x \right)$$

$$\pi_{\mathbb{I}}(\mu | x) = \frac{\Gamma\left(\frac{n+2d_0+1}{2}\right)}{\Gamma\left(\frac{1}{2}\right) \Gamma\left(\frac{n+2d_0}{2}\right)} \left(1 + \frac{\left(\frac{\mu - \left(\frac{n+\frac{1}{2}}{d_0} \right)^{-1} (n\bar{x} + \mu_0)}{\sqrt{\frac{2\beta_0}{n+1} K_0^2}} \right)^2}{(n+2d_0)} \right)^{-\frac{n+2d_0+1}{2}} \frac{1}{\sqrt{2\beta_0} \sqrt{n+1} K_0}$$

$$= \mathbb{I}_{\mathbb{I}} \left(\left(\frac{\mu - \mu_x}{\sqrt{\frac{2\beta_0}{n+1} K_0^2}} \right)^2 \geq \left(\frac{\mu_0 - \mu_x}{\sqrt{\frac{2\beta_0}{n+1} K_0^2}} \right)^2 \mid x \right)$$

$$t \sim t_x \quad t^2 \sim F(1, d)$$

$$= 1 - F\left(1, n+2d_0, \left(\frac{\mu_0 - \mu_x}{\sqrt{\frac{2\beta_0}{n+1} K_0^2}} \right)^2\right)$$

- problems with MAP

① - suppose $\lambda = \Delta(\theta)$ where Δ is 1-1 and smooth

- then posterior of Δ is

$$\pi_{\Delta}(\Delta^{-1}(x) | x) \propto J_{\Delta}(\Delta^{-1}(x))$$

where $J_{\Delta}(\theta) = (\det(d\Delta(\theta)))^{-1}$

- if $J_{\Delta}(\theta)$ is not constant in θ then

$$\Delta_{\text{map}}(x) \neq \Delta(\theta_{\text{map}}(x)) \text{ (generally)}$$

and similarly for hpd regions

- we say MAP inferences are not invariant under reparametrization.

eg $x = (x_1, \dots, x_n) \sim \text{Bernoulli}(\theta)$

- $\theta \sim U(0,1)$

$$\pi(\theta) f_{\theta}(x) \propto \theta^{n\bar{x}} (1-\theta)^{n(1-\bar{x})}$$

$$\therefore \theta | x \sim \text{beta}(n\bar{x}+1, n(1-\bar{x})+1)$$

$$\theta_{\text{map}}(x) = \frac{a-1}{a+b} = \frac{n\bar{x}}{n+2}$$

- $\lambda = \theta^n$, $\theta = x^{1/2}$, $d\theta = \frac{1}{2} x^{-1/2}$

$\lambda_{\text{map}}(x) = \left(\frac{n\bar{x} - 1}{n+1} \right)^2 \neq \tau_{\text{map}}^2$

② What is the evidence that τ_0 is true?

- implicitly it is $\pi_{\tau_0}(\tau_0 | x)$

- but this doesn't behave appropriately