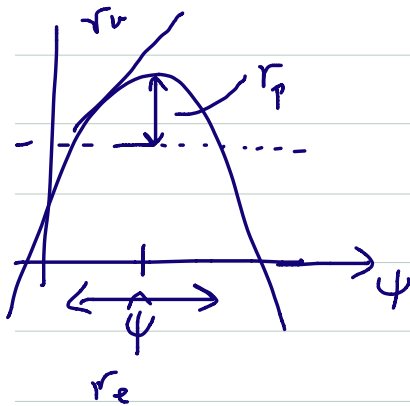


$$\theta = (\psi, \lambda) \quad \psi \in \mathbb{R}$$

$$3 \text{ approx}^{\text{ns}} : \pm \sqrt{2\{l_p(\hat{\psi}) - l_p(\psi)\}} = r_p(\psi)$$

$$\sim N(0, 1) \text{ under } f(y; \theta)$$



$$(\hat{\psi} - \psi) j_p^{1/2}(\hat{\psi}) = r_e(\psi)$$

$$\sim N(0, 1) \text{ under } f(y; \theta)$$

$$l'_p(\psi) j_p^{-1/2}(\hat{\psi}) = r_u$$

↓ all 6
 glm($r \sim .$, data = urine, family = binomial) $\sim N(0, 1)$ under $f(y; \theta)$

Coefficients

	Σ_{st} $\hat{\psi}$	Std Σ $j_p^{1/2}(\hat{\psi})$	Z $\hat{\psi} / j_p^{1/2}$	p -val
constant				
gravity				
ph	-0.49	0.57	-0.87	0.38
osmo				

#6 calc Under $f(y; \psi=0, \lambda)$ obs $\approx .0012$ ^{***}

from a std. Normal

Null deviance	105.17	on 76
residual deviance	57.56	on 70

$$2(l(\hat{\theta}) - l(\theta_0)) \sim \chi_6^2 \quad \theta = (\theta_1, \dots, \theta_6)$$

under $f(y; \theta_0)$ ($\theta_0 = \underline{0}$)

If we fit just 5 covariates
new resid. deviance & their difference

$$\text{is } W_p = 2\{l_p(\hat{\psi}) - l_p(\psi)\} \sim \chi_1^2$$

if $\psi = 0$
 $\psi = (\theta_6)$

- Using either r_e or r_f to test if
 $\psi = 0$.

- Confidence interval for ψ

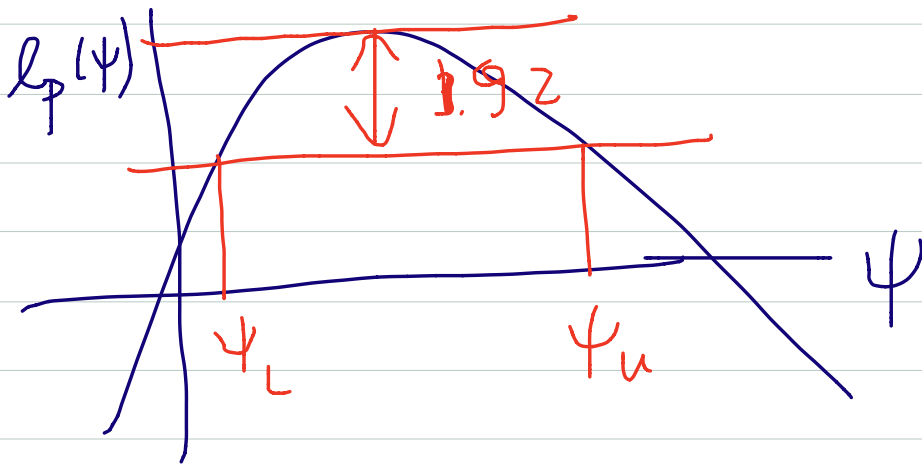
$$i) \quad \hat{\psi} \pm 1.96 \times \widehat{s.e.}(\hat{\psi}) \approx 95\% \text{ CI}$$

\uparrow
normal

$$ii) \quad w_p(\psi) = 2 \{l_p(\hat{\psi}) - l_p(\psi)\} \sim \chi_1^2$$

$$\{\psi: w_p(\psi) \leq 3.84\} \quad 95\% \text{ CI for } \psi$$

$$Pr(\chi_1^2 \leq 3.85) = 0.95$$



Effects of param. \perp $O_p\left(\frac{1}{\sqrt{n}}\right)$

$$\hat{\lambda}_\psi - \lambda = \hat{\lambda} - \lambda + i_{\lambda\lambda}^{-1} i_{\lambda\psi} (\hat{\psi} - \psi) + o_p\left(\frac{1}{\sqrt{n}}\right)$$

$$l_\lambda(\psi, \hat{\lambda}_\psi) = 0$$

$$= \cancel{l_\lambda(\hat{\psi}, \hat{\lambda})} + (\psi - \hat{\psi}) l_{\lambda\psi}(\hat{\psi}, \hat{\lambda}) + (\hat{\lambda}_\psi - \hat{\lambda}) l_{\lambda\lambda}(\hat{\psi}, \hat{\lambda})$$

$$(\hat{\lambda}_\psi - \hat{\lambda}) = -\hat{l}_{\lambda\lambda}^{-1} (-\hat{l}_{\lambda\psi}) (\hat{\psi} - \psi)$$

$$= i_{\lambda\lambda}^{-1} i_{\lambda\psi} (\hat{\psi} - \psi) + o_p(1)$$

If $\hat{\lambda}_\psi \equiv \hat{\lambda}$, then constant in ψ

$$l_p(\psi, \hat{\lambda}_\psi) = l(\psi, \hat{\lambda})$$

If $\hat{\lambda}_\psi$ varies slowly in ψ ,
then inference based on profile
is closer to its limiting form.

To make precise, need to do
higher order expansions.

$$\begin{pmatrix} \hat{\psi} - \psi \\ \hat{\lambda} - \lambda \end{pmatrix} \sim N \left(\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} i^{\psi\psi} & i^{\psi\lambda} \\ i^{\lambda\psi} & i^{\lambda\lambda} \end{pmatrix} \right)$$

$i^{\psi\lambda} = 0$ then $i^{\lambda\psi} = 0$ &

$\hat{\psi}$ $\hat{\lambda}$ a. independent

Example

BNC: $y_i \sim N(\mu_i, \sigma^2)$

i) $\mu_i = \alpha + \beta x_i$ $\mu_i = \gamma + \delta(x_i - \bar{x})$

$$\hat{\alpha} = \bar{y} - \hat{\beta} \bar{x} \quad \hat{\gamma} = \bar{y} \quad \boxed{Y \perp \delta}$$

$$\hat{\beta} = \frac{\sum (x_i - \bar{x}) y_i}{\sum (x_i - \bar{x})^2} = \hat{\delta}$$

$$y_i = x_i^T \beta + \sigma e_i \quad e_i \sim N(0, 1)$$

$$i(\beta, \sigma^2) = \begin{pmatrix} \frac{X^T X}{\sigma^2} & 0 \\ 0 & \frac{n}{2\sigma^4} \end{pmatrix} \leftarrow \text{ntbc}$$

$\beta \perp \sigma^2$ always for N

$X^T X$ is diag. then $\beta_j \perp \beta_k$

$$\hat{\sigma}_{\beta}^2 = \frac{1}{n} \sum_{i=1}^n (y_i - x_i^T \beta)^2$$

$$\hat{\sigma}^2 = \frac{1}{n} \sum (y_i - x_i^T \hat{\beta})^2$$

$$= \hat{\sigma}_{\beta}^2 + \text{Something}$$

$O_p\left(\frac{1}{n}\right)$ check

$l_p(\psi) \leftarrow$ behaves 'like' a
usual log-likelihood.
(to 1st order)

BUT $\hat{\psi} \not\rightarrow \psi$ $k \rightarrow \infty$

$\Rightarrow l_p(\psi)$ poor if $\dim(\lambda)$ "large"
(too concentrated around ψ)

HW 2 $f(s_1 | s_2; \beta_1)$

in logistic regn.

$$f(y; \beta) \cong \underbrace{f(s_1 | s_2; \beta_1)}_{\text{only } \beta_1 \text{ density}} f(s_2; \beta_2)$$

cond
exp'l fam.

$$f(y; \theta) \propto \underbrace{f(s_1; \theta_1)}_{\text{marg.}} f(s_2 | s_1; \theta)$$

← transf.