

Solutions to Exercises on Decision Theory

(a) We have $\bar{X}(w) = \{0, 1\}$ and

$$\sum_{x \in \{0, 1\}} h(x, \theta) S(x, d; \theta) = h(x=0, \theta) S(x=0, d; \theta) + h(x=1, \theta) S(x=1, d; \theta)$$

	$\theta = a$ ($\bar{X}(\theta) = 1$)	$\theta = b$ ($\bar{X}(\theta) = 0$)	$\theta = c$ ($\bar{X}(\theta) = 0$)
$x=0$	0	1	1
$x=1$	$\frac{1}{2}$	$\frac{1}{2}$	$\frac{1}{2}$
$x=2$	$\frac{2}{3}$	$\frac{1}{3}$	$\frac{1}{3}$

$$R(\theta, \delta) = \sum_{x \in \{0, 1, 2\}} \int_{\theta \in \{a, b, c\}} h(x, \theta) S(x, d; \theta) P_\theta(dx)$$

$$\theta = a \Rightarrow \frac{1}{3} \cdot 0 + \frac{1}{3} \cdot \frac{1}{2} + \frac{2}{3} \cdot \frac{1}{3} = \frac{2}{3} = \frac{7}{12}$$

$$\theta = b \Rightarrow \frac{1}{3} \cdot 1 + \frac{2}{3} \cdot \frac{1}{2} + 0 \cdot \frac{1}{3} = \frac{2}{3}$$

$$\theta = c \Rightarrow 0 \cdot 1 + \frac{1}{3} \cdot \frac{1}{2} + \frac{2}{3} \cdot \frac{1}{3} = \frac{2}{3} = \frac{7}{12}$$

(b) The MLE of θ is $\theta(1) = a, \theta(2) = b, \theta(3) = c$

The profile MLE of \bar{X} is $\bar{X}(\theta(1)) = 1, \bar{X}(\theta(2)) = 0, \bar{X}(\theta(3)) = 0$ or $\bar{X}(\theta(1)) = 0, \bar{X}(\theta(2)) = 0, \bar{X}(\theta(3)) = 0$ so it can be thought of as a profile MLE as it is not unique. Using the first MLE,

$$R(\theta, d) = \sum_{x \in \{0, 1, 2\}} h(x, \theta) P_\theta(dx)$$

$$\theta = a \Rightarrow P_a(d(1) = 0) = P_a(x=0) = 7/12$$

$$\theta = b \Rightarrow P_b(d(2) = 1) = P_b(x=1) = 1/3$$

$$\theta = c \Rightarrow P_c(d(3) = 1) = P_c(x=1) = 0$$

(c) $R(a, s) < R(a, d)$ but $R(b, s) > R(b, d)$
so neither is preferred to the other.

(d) We have that when x is known the likelihood is known and conversely when the likelihood is known then x is known. Therefore x is a m.s.s. Note that the conditional distribution of x given x is degenerate at x so $S_x = S$ and $d_x = d$ and there is no randomization.

(e) To be unbiased d has to satisfy, for every $\theta, \theta' \in \Theta$

$$R(\theta, d) = \sum_{\xi \in \{1, 2, 3\}} \text{Loss}(\theta, d(\xi)) P_\theta(d = \xi)$$

$$\theta = a, \theta' = b, P(\theta) = 0$$

$$= \frac{1}{3} \cdot 1 + \frac{1}{3} \cdot 0 + \frac{1}{3} \cdot 0 = \frac{1}{3}$$

and note $R(a, d) = 2/3 > 1/3$ and so d is not unbiased.

3

$$\textcircled{2} \text{ (a) } R(a, d) = \frac{1}{4} L(a, a) + \frac{1}{4} L(a, a) + 0 \cdot L(a, a) + \frac{1}{2} L(a, b)$$

$$= \frac{1}{2}$$

$$R(b, d) = \frac{1}{2} L(b, a) + 0 L(b, a) + \frac{1}{4} L(b, a) + \frac{1}{4} L(b, b)$$

$$= \frac{1}{2} + \frac{1}{4} = \frac{3}{4}$$

(b) Consider the decision function given by $d_0(1) = b$, $d_0(2) = a$, $d_0(3) = b$, $d_0(4) = a$. The

$$R(a, d_0) = \frac{1}{4} L(a, b) + \frac{1}{4} L(a, a) + 0 L(a, b) + \frac{1}{2} L(a, a)$$

$$= \frac{1}{4}$$

$$R(b, d_0) = \frac{1}{2} L(b, b) + 0 L(b, a) + \frac{1}{4} L(b, b) + \frac{1}{4} L(b, a)$$

$$= \frac{1}{4}$$

Therefore $R(\theta, d_0) < R(\theta, d_1) \quad \forall \theta$ and d_0 is not admissible.

$$\textcircled{2} \text{ (c) } \tau(d) = \frac{1}{4} \cdot \frac{1}{2} + \frac{3}{4} \cdot \frac{3}{4} = \frac{1}{8} + \frac{9}{16} = \frac{11}{16}$$

(d) We first need to determine the posterior distribution of θ for each data value.

Posterior distribution

4

$$x=1 \quad \theta=a \quad \frac{\frac{1}{4} \cdot \frac{1}{4}}{\left(\frac{1}{4} \cdot \frac{1}{4} + \frac{3}{4} \cdot \frac{1}{4}\right)} = 1/7$$

$$\theta=b \quad \frac{\frac{3}{4} \cdot \frac{1}{4}}{\left(\frac{1}{4} \cdot \frac{1}{4} + \frac{3}{4} \cdot \frac{1}{4}\right)} = 6/7$$

$$x=2 \quad \theta=a \quad \frac{\frac{1}{4} \cdot \frac{1}{4}}{\frac{1}{4} \cdot \frac{1}{4}} = 1$$

$$\theta=b \quad \frac{\frac{3}{4} \cdot 0}{\frac{1}{4} \cdot \frac{1}{4}} = 0$$

$$x=3 \quad \theta=a \quad \frac{\frac{1}{4} \cdot 0}{\frac{3}{4} \cdot \frac{1}{4}} = 0$$

$$\theta=b \quad \frac{\frac{3}{4} \cdot \frac{1}{4}}{\frac{3}{4} \cdot \frac{1}{4}} = 1$$

$$x=4 \quad \theta=a \quad \frac{\frac{1}{4} \cdot \frac{1}{4}}{\left(\frac{1}{4} \cdot \frac{1}{4} + \frac{3}{4} \cdot \frac{1}{4}\right)} = 2/5$$

$$\theta=b \quad \frac{\frac{3}{4} \cdot \frac{1}{4}}{\left(\frac{1}{4} \cdot \frac{1}{4} + \frac{3}{4} \cdot \frac{1}{4}\right)} = 3/5$$

$$\text{Now } \int_{\Theta} L(\theta, a) \delta(x, da) = \delta(x, \{a\}) L(\theta, a) + \delta(x, \{b\}) L(\theta, b)$$

$$= \delta(x, \{a\}) L(\theta, a) + (1 - \delta(x, \{a\})) L(\theta, b)$$

When $x=1$ posterior risk is

$$(1 - \delta(1, \{a\})) \frac{1}{7} + \delta(1, \{a\}) \frac{6}{7} = \frac{1}{7} + \frac{5}{7} \delta(1, \{a\})$$

and this is minimized by taking $\delta(1, \{a\}) = 0$

When $x=2$ posterior risk is

$$(1 - \delta(2, \{a\})) \cdot 1 + \delta(2, \{a\}) \cdot 0 = 1 - \delta(2, \{a\})$$

and this is minimized by taking $\delta(2, \{a\}) = 1$

When $x=3$ posterior risk is

$$(1 - s(3, \{a\})) \cdot 0 + s(3, \{a\}) \cdot 1 = s(3, \{a\})$$

and this is minimized by taking $s(3, \{a\}) = 0$.

When $x=4$ posterior risk is

$$(1 - s(4, \{a\})) \cdot \frac{2}{5} + s(4, \{a\}) \cdot \frac{3}{5} = \frac{2}{5} + s(4, \{a\}) \cdot \frac{1}{5}$$

and this is minimized by taking $s(4, \{a\}) = 0$.

Therefore the Bayes rule is nonrandomized and is given by

$$\begin{aligned} d(1) &= b \\ d(2) &= a \end{aligned}$$

$$\begin{aligned} d(3) &= b \\ d(4) &= b \end{aligned}$$

$$R(\theta, d) = \sum_{x=1,2,3,4} L(\theta, d(x)) P_{\theta}(d(x))$$

$$\begin{aligned} \theta = a & \\ &= \frac{1}{4} \cdot 1 + \frac{1}{4} \cdot 0 + 0 \cdot 1 + \frac{1}{2} \cdot 1 = 3/4 \end{aligned}$$

$$\begin{aligned} \theta = b & \\ &= \frac{1}{2} \cdot 0 + 0 \cdot 1 + \frac{1}{4} \cdot 0 + \frac{1}{4} \cdot 0 = 0 \end{aligned}$$

d is admissible because to beat it another S would have to have $R(b, S) = 0$ which means it could only differ from d when $x=2$ which would choose a with some positive probability which would make $R(a, S) > R(a, d)$.

So $\mathbb{I}(\theta) = 0$ and $\mathbb{I}(\theta) = 1$ with

loss $L_{oss}(\theta, \eta) = \mathbb{I}(\theta) \eta$. Δ takes the

form
$$\delta_{P_1, P_2}(x, \eta) = \begin{cases} P_1, & x=1, \eta=1 \\ 1-P_1, & x=1, \eta=1/2 \\ P_2, & x=0, \eta=1 \\ 1-P_2, & x=0, \eta=1/2 \end{cases}$$

$$R(\theta, \delta_{P_1, P_2}) = \sum_{\eta \in \{0, 1/2\}} \sum_{x \in \{0, 1\}} L_{oss}(\theta, \eta) \delta_{P_1, P_2}(x, \eta) P_\theta(x)$$

$$= (L_{oss}(\theta, 1)P_1 + L_{oss}(\theta, 1/2)(1-P_1))P_\theta(\eta=1) + (L_{oss}(\theta, 1)P_2 + L_{oss}(\theta, 1/2)(1-P_2))P_\theta(\eta=1/2)$$

$$= \begin{cases} P_1 \frac{1}{2} + P_2 \frac{1}{2}, & \theta = 1/2 \\ (1-P_2), & \theta = 1 \end{cases}$$

$$\max_{\theta} R(\theta, \delta_{P_1, P_2}) = \begin{cases} \frac{P_1 + P_2}{2} & \text{when } \frac{P_1 + P_2}{2} \geq 1 - P_1 \text{ i.e. } P_1 \geq \frac{2}{3} - \frac{P_2}{3} \\ 1 - P_1 & \text{otherwise.} \end{cases}$$

$$\therefore \min_{P_1, P_2} \max_{\theta} R(\theta, \delta_{P_1, P_2}) = \frac{1}{3} \quad \left| \begin{array}{l} \text{min } \frac{P_1 + P_2}{2} \text{ when } P_1 = \frac{2}{3} - \frac{P_2}{3} \\ \text{and } P_2 = 0 \text{ equals } 1/3 \\ \text{and similarly min } (1 - P_1) \text{ when } P_1 = 2/3 \end{array} \right.$$

by $\delta_{\frac{2}{3}, 0}$ and so randomization is necessary to reduce maximum risk

(a) Let $G = \{g, g^2, g^3\}$ where $g_1 = 1 \rightarrow 2 \rightarrow 3 \rightarrow 1, g_2 = 1 \rightarrow 3 \rightarrow 2 \rightarrow 1, g_3 = g_1^{-1}$.
 Then clearly $P_{g_i} \circ g_j^{-1} \in \Sigma_{\mathcal{C}} = \{g, g^2, g^3\} \forall g_i \in G, g_j \in G$.
 Since G is the largest group of 1-1 transformations on $\Sigma_{1,2,3}$ this is the largest group leaving the model invariant.

(b) We have that the group \bar{G} of transformations on \mathcal{C} is the set of all permutations on $\mathcal{C} = \{a, b, c\}$.
 Since \bar{G} acts transitively on \mathcal{C} this implies that this is a group model.

(c) Since $\bar{\pi}(\theta_1) = \bar{\pi}(\theta_2)$ iff $\theta_1 = \theta_2$ we have that $\bar{\pi}(g(\theta_1)) = \bar{\pi}(g(\theta_2))$ whenever $\theta_1 = \theta_2$ and so $\bar{\pi}$ is equivariant.

Suppose $\bar{\pi}(\theta_1) = \bar{\pi}(\theta_2)$ then $\theta_1, \theta_2 \in \{a, b\}$ or $\theta_1 = \theta_2 = c$. But $\bar{g}(a) = b, \bar{g}(b) = c, \bar{g}(c) = a$ is not $\bar{g} \in \bar{G}$ but while $\bar{\pi}(a) = \bar{\pi}(b)$ we have $\bar{\pi}(\bar{g}(a)) = \bar{\pi}(b) = 1 \neq \bar{\pi}(\bar{g}(b)) = \bar{\pi}(c) = 0$.
 Therefore $\bar{\pi}$ is not equivariant.

(d) Since $\bar{\pi}(\theta) = \theta$ and it is equivariant we have $\bar{G} = \bar{G}_*$. Then noting $\text{Loss}(\theta, \psi) = 1$ whenever $\psi \neq \theta$ and $\text{Loss}(\theta, \psi) = 0$ when $\psi = \theta$ we have $\text{Loss}(\bar{g}(\theta), \bar{g}(\psi)) = 0$ when $\theta = \psi$ and since \bar{g} is 1-1 $\bar{g}(\theta) \neq \bar{g}(\psi)$ when $\theta \neq \psi$ so $\text{Loss}(\bar{g}(\theta), \bar{g}(\psi)) = 1 = \text{Loss}(\theta, \psi)$ which proves the loss is invariant.

(e) The MLE is given by $\hat{\theta}(1) = b, \hat{\theta}(2) = c, \hat{\theta}(3) = a$.
 Now $\hat{\theta}(x) = \hat{\theta}(y)$ iff $x = y$ so if $\hat{\theta}(x) = \hat{\theta}(y)$ we have $\hat{g}(x) = \hat{g}(y)$ and conversely so the MLE is equivariant.

To determine the risk of the MLE we need only do this for one value of θ because \bar{G} is transitive on \mathcal{C} . So $R(\theta, \hat{\theta}) = R(a, \hat{\theta}) = \sum_{\psi} L(a, \hat{\theta}(\psi)) P_{\theta}(\psi) = P_{\theta}(1, 3) + P_{\theta}(2, 3) = 1/6 + 1/3 = 1/2$.

Any other equivariant estimator d has constant risk $R(\theta, d) = P_d(d(x) = b) + P_d(d(x) = c)$. Now suppose $d(b) = d(c)$ and suppose $g_1(x) = x, g_2(x) = 3 - x$ so $d(g_1(x)) = d(x) = d(g_2(x)) = d(3-x)$ and so $d(x) = d(3-x) = d(x)$ and d is constant. But if d is constant then $d(x) = d(g_1(x)) = \bar{g}(d(x))$ and if $\bar{g} = a \rightarrow b, b \rightarrow c, c \rightarrow a$ this cannot hold no matter $d(x)$ equals. A similar argument shows that d must be 1-1 (can't have $d(x) = d(y)$ or $d(x) = d(c)$). Then we must have $P_d(d(x) = b) + P_d(d(x) = c) = 1/6 + 1/3 = 1/2$ (these are the smallest error probabilities when $\theta = a$). Therefore $\hat{\theta}$ is optimal equivariant.

(f) For general invariant S we need only consider the risk when $\theta = a$. Now

$$\sum_{g_1, g_2, g_3} L(a, \pi) S(x, d\pi) = S(x, \pi b) + S(x, \pi c) = 1 - S(x, \pi a)$$

$$\text{so } R(a, S) = E_a(1 - S(x, \pi a)) = 1 - \frac{1}{6} S(1, \pi a) - \frac{1}{3} S(2, \pi a) - \frac{1}{3} S(3, \pi a)$$

and note by invariance $S(2, \pi a) = S(1, \pi c)$ under g_1 and $S(3, \pi a) = S(1, \pi b)$ under g_2 . Therefore

$$\begin{aligned} R(a, S) &= 1 - \frac{1}{6} S(1, \pi a) - \frac{1}{3} S(1, \pi c) - \frac{1}{3} S(1, \pi b) \\ &= 1 - \frac{1}{6} S(1, \pi a) - \frac{1}{3} S(1, \pi c) - \frac{1}{2} (1 - S(1, \pi a) - S(1, \pi c)) \\ &= \frac{1}{2} + \frac{1}{3} S(1, \pi a) + \frac{1}{6} S(1, \pi c) \geq \frac{1}{2} \end{aligned}$$

and so the MLE is optimal invariant.